

Particle Simulation of Electrodynamic Aerobraking in a Hypersonic Rarefied Regime

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Abstract. To investigate the electrodynamic aerobraking in a hypersonic rarefied regime, the electromagnetic flow control on a reentry Hayabusa-shape capsule entering a pure nitrogen atmosphere is investigated using the Direct Simulation Monte Carlo method with a simple ion particle movement method like the Particle-In-Cell method. As a results, the generated electrodynamic force is found to be enough strong to use the electrodynamic aerobraking.

Keywords: Hypersonic Rarefied Flow, Reentry, Aerobraking

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INTRODUCTION

Aerobraking is a promising orbital insertion technique in planetary exploration missions because the aeroassisted spacecraft deceleration through a planetary atmosphere can save huge on-board propellant required for the deceleration using a chemical motor. In 2002, The Mars Odyssey mission [1] has successfully demonstrated the aerobraking orbital maneuvering from a Mars orbit after the orbital insertion using a chemical motor. In the aerobraking mission, on-board flat panels without any Thermal Protection System (TPS) was expanded to control increasing aerodynamic drag. However, a structure without any TPS is not applicable to a direct aerobraking orbital insertion (that is, aerocapture) because a spacecraft are exposed to severe convective and radiative heating. Although ballute technology [2] is proposed to control aerodynamic drag at a high altitude in which heat load is small because of rarefied atmosphere, the TPS problem has been still one of obstacles to realize the aerocapture technology.

An alternative to existing aerobraking technology can be achieved by actively controlling aerodynamic drag through an electromagnetic force which is generated by applying a magnetic field to a partially ionized flow behind a bow shock around a spacecraft [3, 4, 5]. Figure 1 shows a schematic view of electrodynamic aerobraking. A magnet embedded in a blunt body forms a dipolar-like magnetic field \mathbf{B} around the body, and a circumferential current J_θ is induced according to Ohm's law through the interaction between \mathbf{B} and the weakly ionized flow \mathbf{v} behind a bow shock. The electromagnetic effect generates the Lorentz force $\mathbf{J} \times \mathbf{B}$ against the flow direction, and the shock standoff distance is enlarged: the effect reduces aerodynamic heating and increases aerodynamic drag because the effective radius of curvature of the body increases from the viewpoint of the bow shock (in practice, $\mathbf{J} \times \mathbf{B}$ acting on the fluid exerts a reaction force on the magnet [5]). Moreover, electrodynamic aerobraking is more advantaged than aerodynamic aerobraking with a structure because drag is easily controllable by changing the magnetic strength.

To make the electromagnetic flow control effective, the magnetic interaction parameter [6] Q requires a condition by which

$$Q = (\sigma B^2 L) / (\rho_\infty v_\infty) \gtrsim 1, \quad (1)$$

where σ , $\rho_\infty v_\infty$, and L respectively represent electric conductivity, the momentum of the flow, and the characteristic length of the body. To apply this flow control to the reentry TPS, many researchers studied this topic in the 1950–1970s theoretically [3, 4, 5] and experimentally [7, 8, 9], and these early experiments have shown the luminous shock layer enlargement [7], heat flux reduction [8], and drag increase [9] through the electromagnetic effect. However the electrodynamic TPS has not been realized because the applied field required for $Q > 1$ is too strong for actual applications. Nevertheless, recent technological advancements of superconductive materials has made it possible to develop a magnet with the necessary strength: an on-board magnet or coil can be applied to an active TPS for a reentry vehicle. For those reasons, the concept of the electromagnetic flow control has been revisited in the reentry aerodynamic research field, and experimental [10, 11, 12] and numerical [13, 14, 15, 16, 17, 18] studies have been carried out in recent years.

Although these previous works have mostly clarified physical mechanisms of the electromagnetic flow control and approved its applicability to the reentry TPS in hypersonic continuum regimes, the flow control may be more suitable to aerocapture missions at more higher altitudes because the electrodynamic braking effect is more significant rather than its heat flux reduction effect [17, 18].

However the obtainable electrodynamic force is unknown in such a hypersonic rarefied regime. To investigate this topic, the present preliminary study simulates the electromagnetic flow control on a reentry Hayabusa-shape capsule entering a pure nitrogen atmosphere at the altitude of 80 km using the Direct Simulation Monte Carlo (DSMC) method [19] with a simple ion particle movement method like the Particle-In-Cell (PIC) method.

DSMC METHOD AND PHYSICAL MODEL

DSMC modeling

The present study simulates the flow field around the Hayabusa-shape capsule entering a pure nitrogen atmosphere, whose flow conditions are shown in Table 1. To simulate this hypersonic rarefied flow, we newly developed the axisymmetric DSMC code including chemical reactions with ionization and inelastic collisions among internal modes. The Ion-Averaged Velocity (IAV) method [20] is used to keep the charge-neutrality, in which electrons move at the ion velocity averaged in each cells. Ozawa et al. [21] recently have proposed the physical models for DSMC simulations in strongly thermochemical nonequilibrium conditions. The present study basically adopted their models to incorporate the thermochemical nonequilibrium effects, and more detailed description is found in [22].

Simple modeling of electromagnetic effect

The present study uses the IAV method, and hence ignores the detailed interaction between the electron movement and applied magnetic field; the Hall and ion slip effects and the resulting generation of the electric field are still not considered, although these effects are significant in rarefied ionized flows. [17, 18] Only interaction between an ion particle and the applied magnetic field are considered using the motion equation for the ion,

$$m_{\text{ion}} d\mathbf{v}_{\text{ion}}/dt = |e| \mathbf{v}_{\text{ion}} \times \mathbf{B}(\mathbf{x}_{\text{ion}}) \quad (2)$$

wherein m_{ion} , \mathbf{v}_{ion} , \mathbf{x}_{ion} , \mathbf{B} , $|e|$ are respectively ion mass, the velocity and location of the ion particle, applied magnetic field at \mathbf{x}_{ion} and elementary charge. And this ion movement according to the electro-motive force $\mathbf{v}_{\text{ion}} \times \mathbf{B}$ is solved using the leap-frog method like the PIC method.

Computational grid and applied field

Figure 2 shows the computational grid and applied magnetic field. The body shape is identical to that of the Hayabusa capsule forebody. The number of the cells are 200×120 . The fine cells are prepared in the axial direction and the minimum size Δz is 0.1 mm which is the order of magnitude of the local mean free path.

Each cells are divided into 16 subcells to reduce the distance of the mean collision separation in selecting collisional pairs [19]. If the number of molecules in a cell is smaller than 20, the virtual subcell method [24] is used instead of searching a molecule-pair in subcells.

The magnetic field \mathbf{B} is applied on $r-z$ plane, in which a circular superconductive current loop embedded in the body is assumed to generate the magnetic field of $B_0=0.5-1$ T at the stagnation point according to the Biot-Savart law.

RESULTS AND DISCUSSION

The present study sets the number of real particles represented by a macro-particle to be $N_0=5 \times 10^{12}$ in no radial weighting region ($r < r_{w,\text{min}}$). The averaged number of macro-particles is 50-200 in any cell, but it is about 10 in the cells near the axis. This value might be too small to capture charged particles correctly whose molar fractions are smaller than 10%. The fluctuations of the solution near the axis are still large although the results are obtained after

approximately 30,000 sampling times (two days computations on a Core i7 personal computer). More sampling times and macro-particles or species weighting method [25] may be necessary to obtain more smooth results.

Ionizing flow without magnetic field

Figures 3 and 4 show temperatures (heavy particle translational T_{trans} , rotational T_{rot} , vibrational T_{vib} , and electron translational T_e) and molar fractions on the $\xi=3$ line (ξ is grid number in the radial direction); the results on the axis are not shown because the fluctuations of the solution are still large. Although the fluctuation of T_e is still large, the appearance of thermochemical nonequilibrium almost agrees with the results of the Stardust reentry [21, 23] whose flow conditions are very similar to those of this study.

The molar fraction of electron and σ are approximately 6% and 3,000 S/m (estimated using continuum cross sections of ionized nitrogen gas [27, 28]) near the stagnation point. As a result, this flow should generate strong electrodynamic force because Q parameter is estimated to be 5340 ($\gg 1$) if $B=1$ T.

Electromagnetic effect

Two cases of $B_0=0.5$ and 1 T are investigated. Figures 5 and 6 show the comparison of T_{trans} between applied and not-applied. The electro-motive force $v_{\text{ion},r,z} \times \mathbf{B}$ first accelerates ions in the θ direction, and then Lorentz force acting on the ion \mathbf{F}_L is generated on $r-z$ plane by the electro-motive force $v_{\text{ion},\theta} \mathbf{\theta} \times \mathbf{B}$. As a result, this strong F_L enlarges the shock layer in proportion to B^2 , because Q parameter is proportional to B^2 if the detailed interactions (Hall and ion slip effects) between electrons and the magnetic field are ignored.

Figures 7, 8 and 9 show the comparison of T_{trans} , T_e , and the molar fraction of electron on $\xi=3$ line between applied and not-applied cases. The heat flux to the wall will reduce because T_{trans} near the wall decreases with increasing B , although the profile of $B_0=0.5$ T is questionable. The enlargement of the shock layer also enlarges the high T_e region and the resulting ionizing region (due to the avalanche ionization of No.4 in Table.2). As a result, the molar fraction of electron obtainable in $B_0=1$ T becomes four times as large as that of not-applied field.

Drag increment and heat flux reduction

The correct estimation of the electrodynamic drag is difficult because of ignoring the real electron motion due to the usage of the IAV method in this study; Hence F_L exerted on ions is simply doubled on the assumption that electrons receive the Lorentz force identical to that of ions. Axial electrodynamic drag exerted on the superconductive coil are defined as

$$D_L = -2 \int_{\text{all cells}} \sum_{\text{ions}} F_{L,z} dV \quad (3)$$

Figures 10 and 11 show D_L , aerodynamic drag D_A , and heat flux to the body wall. In contrast to the drastic increase of D_L , D_A decreases with B because of the deviation of the flow from the body. Eventually, the total drag increase is 5% in applying $B=1$ T. However, this result is questionable because the shock layer enlargement is very large. More discussions will be necessary to estimate the electrodynamic drag correctly. As was expected, the heat flux decreases with B , and 15% reduction is achievable in $B=1$ T.

SUMMARY

To investigate the electrodynamic aerobraking in a hypersonic rarefied regime, the electromagnetic flow control on a reentry Hayabusa-shape capsule entering a pure nitrogen atmosphere is investigated using the Direct Simulation Monte Carlo method with a simple ion particle movement method like the Particle-In-Cell method. As a result, the generated electrodynamic force is found to be enough strong to use the electrodynamic aerobraking in the hypersonic rarefied regime: 5% increase of the total drag and 15% reduction of the heat flux are achievable in applying $B=1$ T. However, more correct treatment of the electron motion (e.g., DSMC/PIC/electron-fluid Hybrid method [29, 30]) will be necessary to estimate the electrodynamic drag force correctly, and we will try this method in the future work.

TABLE 1. Flow conditions

Gas	Pure nitrogen
Altitude h	80 km
Flight velocity v_∞	12.3 km/s
Number density n_∞	$3.97 \times 10^{20} \text{ m}^{-3}$
Temperature T_∞	199 K
Body diameter D	40.4 cm
Knudsen number K_{n_∞} (based on D)	1.75×10^{-2}

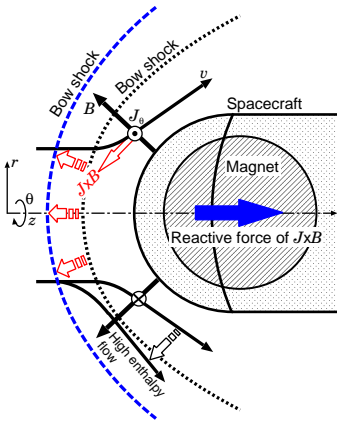


FIGURE 1. Schematic view of the electrodynamic aerobraking.

TABLE 2. Chemical reactions [21]

No.	Reaction
1a	$\text{N}_2 + \text{M} \Rightarrow \text{N} + \text{N} + \text{M}$
1b*	$\text{N}_2 + \text{A} \Rightarrow \text{N} + \text{N} + \text{A}$
1c	$\text{N}_2 + \text{e} \Rightarrow \text{N} + \text{N} + \text{e}$
2	$\text{N} + \text{N} \Leftrightarrow \text{N}_2^+ + \text{e}$
3	$\text{N}_2 + \text{N}^+ \Leftrightarrow \text{N} + \text{N}_2^+$
4	$\text{N} + \text{e} \Rightarrow \text{N}^+ + \text{e} + \text{e}$

M: any third body molecule

A: any third body atom,* [23]

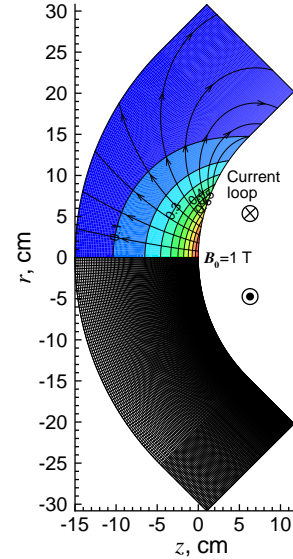


FIGURE 2. Computational grids and applied filed.

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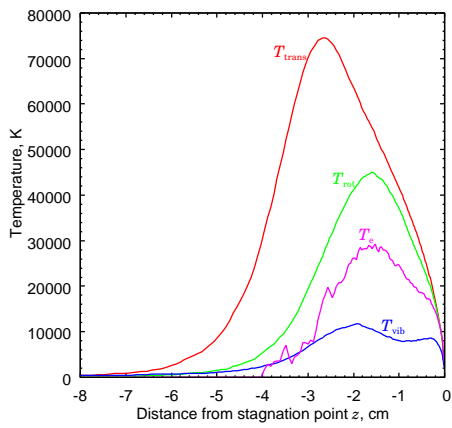


FIGURE 3. Temperature on $\xi=3$ line in ionizing flow

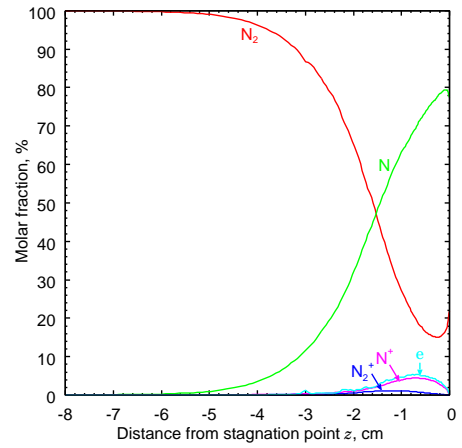


FIGURE 4. Molar fractions on $\xi=3$ line in ionizing flow

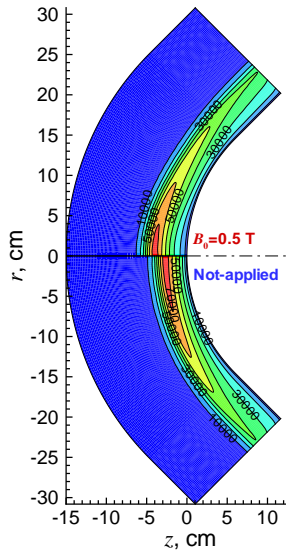


FIGURE 5. T_{trans} [K] contours ($B_0=0.5\text{T}$)

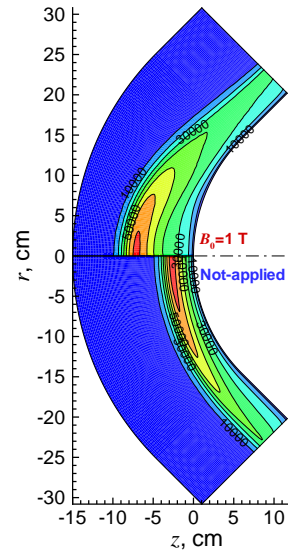


FIGURE 6. T_{trans} [K] contours ($B_0=1\text{T}$)

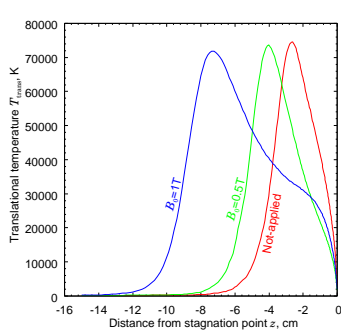


FIGURE 7. T_{trans} on $\xi=3$ line in not- and applied cases

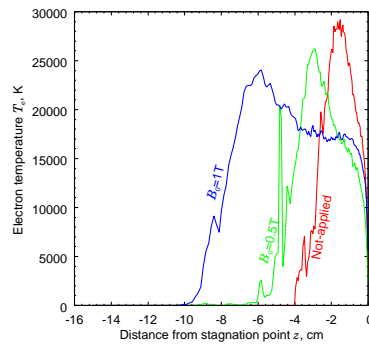


FIGURE 8. T_e on $\xi=3$ line in not- and applied cases

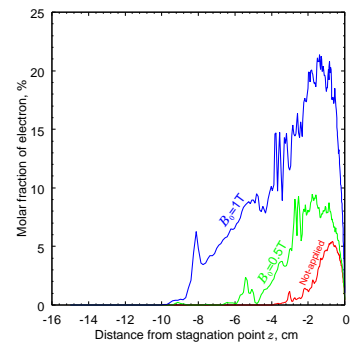


FIGURE 9. Molar fraction of electron on $\xi=3$ line in not- and applied cases

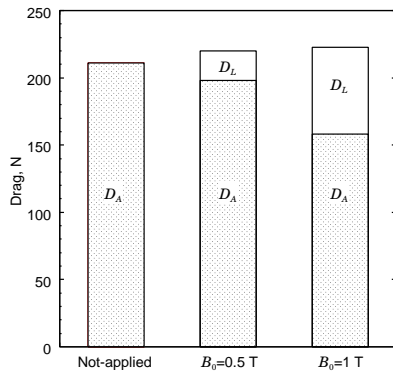


FIGURE 10. Drag force

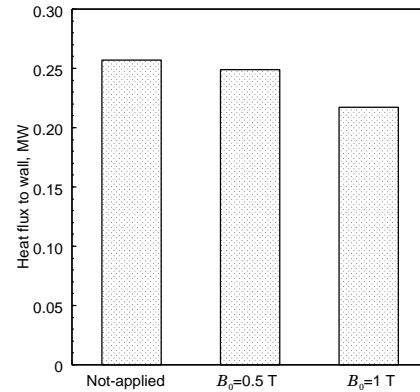


FIGURE 11. Heat flux to wall

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